

According to (3.3) loc. cit., if we transform from (x^1, x^2, \dots, x^n) to (z^1, z^2, \dots, z^n) the functions $\Gamma_{i\alpha}^i$ are transformed as follows:

$$\begin{aligned}\bar{\Gamma}_{i\alpha}^i(z) &= \Gamma_{ij}^i(x) \frac{\partial x^j}{\partial z^\alpha} + \frac{\partial}{\partial z^\alpha} \left(\frac{\partial x^j}{\partial z^i} \right) \frac{\partial z^i}{\partial x^j} \\ &= \Gamma_{ij}^i(x) \frac{\partial x^j}{\partial z^\alpha} + \frac{1}{\Delta} \frac{\partial \Delta}{\partial z^\alpha}\end{aligned}$$

where Δ is the Jacobian, $|\partial x^j / \partial z^i|$ of the transformation. The last equations are the same as

$$\bar{\Gamma}_{i\alpha}^i(z) = \frac{\partial \log \gamma}{\partial x^j} \frac{\partial x^j}{\partial z^\alpha} + \frac{\partial \log \Delta}{\partial z^\alpha} = \frac{\partial}{\partial z^\alpha} \log \bar{\gamma}$$

where we are denoting by $\bar{\gamma}$ the function obtained by substituting the x 's as functions of the z 's in γ and multiplying by Δ . Hence the function γ is a scalar density and

$$\int \gamma dx^1 dx^2 \dots dx^n$$

may be taken as a definition of volume.

AFFINE GEOMETRIES OF PATHS POSSESSING AN INVARIANT INTEGRAL

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Read before the Academy, November 16, 1922

1. In the Riemann geometry volume is defined by the invariant integral $\int \sqrt{g} dx^1 \dots dx^n$ where g is the determinant $|g_{ij}|$. If g' denotes the corresponding function when the coördinates are x'^1, \dots, x'^n , then

$$\sqrt{g'} = \sqrt{g} \Delta, \quad (1.1)$$

where Δ is the Jacobian $\left| \frac{\partial x}{\partial x'} \right|$. When there exists for a geometry of paths a function g satisfying (1.1), we say that the geometry possesses an invariant integral, and g is called a *scalar density*. In a recent note (these PROCEEDINGS, 9, p. 3) Professor Veblen showed that in an affine space for which $S_{ij} = 0$ a scalar density is defined by $\Gamma_{\alpha i}^\alpha = \partial \log \sqrt{g} / \partial x^i$; he calls

such a space *equiaffine*. It is the purpose of this note to show that a *necessary and sufficient condition* that a *geometry of paths* possess an *invariant integral* is that S_{ij} be the curl of a covariant vector, and to derive some consequences of this theorem.

2. Let Γ_{jk}^i be the functions appearing in the equations of the paths (these PROCEEDINGS, Feb., 1922), then the functions $\Gamma_{jk}^{i'}$ for a set of coördinates x' are given by

$$\frac{\partial^2 x^p}{\partial x'^i \partial x'^j} + \Gamma_{qr}^p \frac{\partial x^q}{\partial x'^i} \frac{\partial x^r}{\partial x'^j} = \Gamma_{ij}^{p'}$$
(2.1)

and the curvature tensor is defined by

$$B_{qrs}^p = \frac{\partial \Gamma_{qs}^p}{\partial x^r} - \frac{\partial \Gamma_{qr}^p}{\partial x^s} + \Gamma_{ar}^p \Gamma_{qs}^a - \Gamma_{as}^p \Gamma_{qr}^a$$
(2.2)

By definition we have

$$S_{ij} = B_{\alpha ij}^\alpha = \frac{\partial \Gamma_{\alpha j}^\alpha}{\partial x^i} - \frac{\partial \Gamma_{\alpha i}^\alpha}{\partial x^j}$$
(2.3)

If equation (1.1) be differentiated, we have, in consequence of (2.1),

$$\begin{aligned} \frac{\partial \sqrt{g'}}{\partial x'^i} &= \frac{\partial \sqrt{g}}{\partial x^\alpha} \frac{\partial x^\alpha}{\partial x'^i} \Delta + \sqrt{g} \Delta \frac{\partial^2 x}{\partial x'^i \partial x'^j} \frac{\partial x'^j}{\partial x^\alpha} \\ &= \Delta \sqrt{g} \left(\frac{\partial \log \sqrt{g}}{\partial x^\alpha} \frac{\partial x^\alpha}{\partial x'^i} + \Gamma_{\alpha i}^{\alpha'} - \Gamma_{\alpha q}^{\alpha'} \frac{\partial x^q}{\partial x'^i} \right), \end{aligned}$$

or, by means of (1.1),

$$\frac{\partial \log \sqrt{g'}}{\partial x'^i} - \Gamma_{\alpha i}^{\alpha'} = \left(\frac{\partial \log \sqrt{g}}{\partial x^j} - \Gamma_{\alpha j}^{\alpha'} \right) \frac{\partial x^j}{\partial x'^i}$$
(2.4)

From this equation it follows that

$$\partial \log \sqrt{g} / \partial x^j = \Gamma_{\alpha j}^{\alpha'} - \varphi_j$$
(2.5)

where φ_j is a covariant vector. The conditions of integrability of equations (2.5) are

$$\frac{\partial \Gamma_{\alpha j}^{\alpha'}}{\partial x^i} - \frac{\partial \Gamma_{\alpha i}^{\alpha'}}{\partial x^j} = \frac{\partial \varphi_j}{\partial x^i} - \frac{\partial \varphi_i}{\partial x^j}$$
(2.6)

that is, S_{ij} , as defined by (2.3), is the curl of a vector, φ .

Conversely, if S_{ij} is the curl of a vector, φ_i , we have equations of the form (2.6) and (2.5) in each coördinate system, x and x' , and consequently

equation (2.4) holds. If equations (2.1) be multiplied by $\frac{\partial x'^j}{\partial x^p}$ and summed for p and j , we obtain

$$\Gamma'_{\alpha i} = \Gamma_{\alpha q} \frac{\partial x^q}{\partial x'^i} + \frac{\partial \log \Delta}{\partial x'^i}.$$

By means of this relation, we obtain (1.1) from (2.4), and the theorem of § 1 is proved.

3. In a former paper (these PROCEEDINGS, Aug., 1922) the author considered spaces with corresponding paths and made the restriction in § 1 of that paper that s is the same for all paths. If this restriction be removed, the formulas (3.4) and (3.6) written in the form

$$\bar{\Gamma}_{jk}^i = \Gamma_{jk}^i + \delta_j^i \varphi_k + \delta_{kj}^i \varphi_j \quad (\delta_j^i = \begin{matrix} 1 \text{ for } i = j \\ 0 \text{ for } i \neq j \end{matrix}), \quad (3.1)$$

where φ_i is a covariant vector, give the necessary and sufficient relations between the Γ 's of two geometries of paths so that the paths are in one-to-one correspondence, and (3.7) gives the relations between s and \bar{s} along corresponding paths. Equations (3.1) have been found by Weyl (*Gött. Nach.*, 1921), and also independently by Veblen (these PROCEEDINGS, Dec., 1922); they have interpreted them as the relations between the Γ 's which yield the same paths in a space. Also they have remarked that each choice of the vector φ_i yields an affine space, whereas the paths define a projective space.

In my former paper it was shown that

$$\bar{S}_{ij} = S_{ij} + (n + 1) (\varphi_{ji} - \varphi_{ij}). \quad (3.2)$$

From this equation it follows that if S_{ij} is the curl of a vector, and the vector $\varphi_i/(n + 1)$ is used in (3.1), then $\bar{S}_{ij} = 0$, that is, the space is equiaffine.

By definition the contracted curvature tensor R_{ij} is given by

$$R_{ij} = B_{ij\alpha}^\alpha \quad (3.3)$$

From this it follows that

$$R_{ij} - R_{ji} = S_{ji} \quad (3.5)$$

Hence the above result may be stated as follows:

Among the affine spaces possessing an invariant integral and having corresponding paths, one is equiaffine; for this space the contracted tensor is symmetric.

This result takes the place of the theorem stated in § 5 of my former paper, where an error was made in concluding that S_{ij} is the curl of a vector

for any geometry of paths (cf. my note on this point in the *Bull. Amer. Math. Soc.*, Dec., 1922).

4. The contracted tensor for a Riemann space is symmetric. Consequently if in (3.1) we replace Γ_{jk}^i by their expressions as Christoffel symbols of the second kind for a Riemann space, the functions $\bar{\Gamma}_{jk}^i$ define an affine space possessing an invariant integral. Hence:

The spaces with paths corresponding to the paths of a Riemann space possess an invariant integral.

CLOSED CONNECTED SETS WHICH ARE DISCONNECTED BY THE REMOVAL OF A FINITE NUMBER OF POINTS

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Communicated, October 11, 1922

THEOREM A. *Suppose k is a positive integer and M is a closed connected point set in Euclidean space of two dimensions such that*

(1) *if P_1, P_2, \dots, P_k are any k distinct points of M , then $M - (P_1 + P_2 + \dots + P_k)$ is disconnected.*

(2) *if Q_1, Q_2, \dots, Q_{k-1} are any $(k - 1)$ distinct points of M , then $M - (Q_1 + Q_2 \dots Q_{k-1})$ is connected.*

Under these conditions, M is a continuous curve.¹

Proof.—Let us suppose that M is not connected im kleinen. Then there exists a point P belonging to M and a circle K with centre at P , such that within every circle whose centre is P there exists a point which does not lie together with P in any connected subset of M that lies entirely within K . Let $K_1, K_2 \dots$ denote an infinite sequence of circles with centre at P and radius $r/2n$, where r is the radius of K . Let X_n denote a point within K_n such that X_n and P do not lie together in a connected subset of M which lies entirely within K . Let K' denote a circle with centre at P and radius $3r/4$. It follows with the use of a theorem due to Zoratti² that there is a closed connected set g_n , containing X_n and at least one point of K' not containing P and lying entirely within or on K' . It may easily be proved that there exist point sets t_n, t_n, \dots such that (1) for every i , t_n is a closed connected subset of M having at least one point on K' and at least one point on K_1 but no point within K_1 or without K' , (2) for no values of i and j ($i \neq j$) does t_n have a point in common with t_n . It follows that there exists an infinite sequence of integers q_1, q_2, \dots such that for every i , $q_{i+1} > q_i$ and a closed connected set t and a sequence of closed connected sets $k_{nq_1}, k_{nq_2} \dots$ such that (1) for every i , k_{nq_i} is a subset of t_{nq_i} , (2) each of